

# CONCURRIT: Testing Concurrent Programs with Programmable State-Space Exploration (A DSL for Writing Concurrent Tests)

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# How to write an xUnit-like test for a concurrent program?



- Consider:
  - Mozilla SpiderMonkey JavaScript Engine
    - Used in Firefox browser
    - 121K lines of code
  - Want to test `JS_NewContext`, `JS_DestroyContext`
    - Contain  $2K <$  lines of code

# How to write an xUnit-like test for a *sequential* program?

- Fix inputs → Deterministic test
  - If there is a bug, every run manifests it!

```
// check if any assertion fails
test_Context() {
    ...
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        ...
        JS_DestroyContext(cx);
    }
}
```



# How to write an xUnit-like test for a concurrent program?

- Nondeterminism due to thread schedules
  - **Hard** to specify and control schedule!



```
// check if any assertion fails
test_Context() {

    ... // create 10 threads to run testfunc

}

testfunc() {
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        ...
        JS_DestroyContext(cx);
    }
}
```

# Approaches to testing concurrent programs

## 1. Stress testing: No control over thread schedules

➔ No guarantee about generated schedules

```
// check if any assertion fails
test_Context() {
    Loop 1000 times {
        ... // create 100 threads to run testfunc
    }
}

testfunc() {
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        ...
        JS_DestroyContext(cx);
    }
}
```

# Approaches to testing concurrent programs

1. **Stress testing:** No control over thread schedules

➔ No guarantee about generated schedules

2. **Model checking:** Enumerate all possible schedules

– Too many schedules

➔ Not scalable for large programs!

**Missing:** Programmer has no direct control on thread schedule

- **Key** to effective and efficient testing

# Programmers have often insights/ideas about which schedules to look at

Wan-Teh Chang 2002-08-29 16:08:33 PDT

[Description](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

This bug affects the pthreads version of NSPR, which is used on most Unix platforms.

There is a race condition when we use PR\_Interrupt to interrupt PR\_WaitCondVar.

Suppose thread A is calling PR\_WaitCondVar and thread B is interrupting thread A. The following event sequence is problematic.

**DO NOT READ!**

Thread A	Thread B
=====	=====
Test its interrupt flag	
Set thred->waiting to cvar	
	Set thread A's interrupt flag
	Call pthread_cond_broadcast on thread A's 'waiting' cvar
Call pthread_cond_wait	
=====	

Thread A misses the broadcast and blocks in pthread\_cond\_wait forever.

This can be reproduced with the 'join' test program, at least on Red Hat Linux 6.2.

# Programmers have often insights/ideas about which schedules to look at

[paul.barnetta@smx.co.nz](mailto:paul.barnetta@smx.co.nz) 2009-02-04 13:54:41 PST [Description](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

I have a multi-threaded application that periodically crashes. I maintain a pool of JSContexts: as they're requested from the pool JS\_SetContextThread and JS\_BeginRequest are called; when they're returned JS\_EndRequest and JS\_ClearContextThread are called.

**DO NOT READ!**

The crashes consistently occurs inside js\_GC in the following code block:

```
while ((acx = js_ContextIterator(rt, JS_FALSE, &iter)) != NULL) {
    if (!acx->thread || acx->thread == cx->thread)
        continue;
    memset(acx->thread->gcFreeLists, 0, sizeof acx->thread->gcFreeLists);
    GSN_CACHE_CLEAR(&acx->thread->gsnCache);
}
```

acx always appears to be valid but acx->thread == NULL when the application crashes (which may be in the memset or GSN\_CACHE\_CLEAR line). This shouldn't occur as these lines should be skipped if (!acx->thread)..

What I suspect is happening is that one thread is calling JS\_GC while a second is calling JS\_EndRequest and JS\_ClearContextThread (in returning a context to the pool). The call to JS\_GC will block until JS\_EndRequest finishes.. JS\_GC then resumes.. but while JS\_GC is running JS\_ClearContextThread also runs (no locking is done in this?), **modifying the value of acx->thread** as the code above runs. acx->thread becomes NULL just before it gets dereferenced and the application exits.



# Programmers have often insights/ideas about which schedules to look at

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment 5](#) [[reply](#)] [[-](#)] [[reply](#)] [[-](#)]

At least one problem that I can see from the code is that `js_GC` does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

**DO NOT READ!**

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls `js_DestroyContext` and thread C calls `js_NewContext`.

**Fixed, known schedule for threads A and B**

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch `rt->state` and eventually calls `js_GC`. The latter skips the above check and tries to to take the GC lock.

Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, sets `rt->state` to `LANDING`, runs `the-last-context-cleanup`, runs the GC and then sets `rt->state` to `DOWN`.

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when `rt->state` is `DOWN`.

**Unknown schedule for A and C**

Now the thread C enters the picture. It discovers under the GC lock in `js_NewContext` that the newly allocated context is the first one. Since `rt->state` is `DOWN`, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Inserting sleeps to enforce a schedule

## Sleeps:

- **Lightweight and convenient tool** for programmer
  - **BUT:** Ad hoc, not reliable for long, complex schedules.
- ➔ **Need: Formal and robust** way to describe schedules!

With the patched NSPR library, run the 'join' test.  
The events will happen at the following time instants:

Thread A	Thread B
=====	=====
T0: Test its interrupt flag	T0: Sleep 1 second
T0: Set thred->waiting to cvar	
T0: Sleep 2 seconds	
	T1: Set thread A's interrupt flag
	T1: Call pthread_cond_broadcast on thread A's 'waiting' cvar
T2: Call pthread_cond_wait	

- 

I have a multi-threaded application that periodically crashes, giving the following assertion error:

```
$ ./a.out
```

```
Assertion failure: rt->state == JSRTS_UP || rt->state == JSRTS_LAUNCHING, at
jscntxt.cpp:465
```

Steps to Reproduce:

Below is a simple application that exhibits the problem (me) when run directly from the command line:

```
#define THREADS 100
```

```
static void * testfunc(void *ignored) {
```

```
JSContext *cx = JS_NewContext(rt, 0x1000);
```

```
if (cx) {
```

```
JS BeginRequest(cx);
```

```
JS DestroyContext(cx);
```

```
return NULL;
```

}

```
/* Uncommenting this to guarantee there's always at least
 * one context in the runtime prevents this problem. */
// JSContext *cx = JS_NewContext(rt, 0x1000);
```

```
for (i = 0; i < THREADS; i++) {
    pthread_join(thread[i], NULL);
}
```

It seems to be very sensitive to timings as I have trouble reproducing the issue in gdb. For me to trigger it there I just need create/destroy more contexts per thread, but YMMV.

# Possible buggy schedule from bug report

**DO NOT READ!**

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment 5](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

At least one problem that I can see from the code is that js\_GC does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls js\_DestroyContext and thread C calls js\_NewContext.

**Fixed, known schedule for threads A and B**

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch rt->state and eventually calls js\_GC. The latter skips the above check and tries to to take the GC lock.

Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, sets rt->state to LANDING, runs the-last-context-cleanup, runs the GC and then sets rt->state to DOWN.

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when rt->state is DOWN.

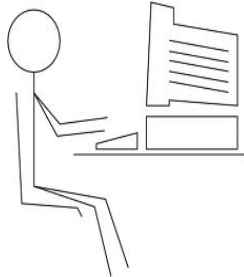
**Unknown schedule for A and C**

Now the thread C enters the picture. It discovers under the GC lock in js\_NewContext that the newly allocated context is the first one. Since rt->state is DOWN, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Concurrit: A DSL for writing concurrent tests



Insights/ideas about  
thread schedules



## Software Under Test

```
#define THREADS 100

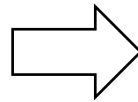
static void * testfunc(void *ignored) {

    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        JS_BeginRequest(cx);
        JS_DestroyContext(cx);
    }

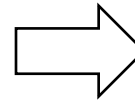
    return NULL;
}
```

Systematically  
explore

**all-and-only**  
thread schedules  
specified by DSL



+



Test in  
Concurrit DSL

Specify a set of schedules in **formal**,  
**concise**, and **convenient** way

# Unit-testing programs with Concurrit

(What about integration tests?: Wait for conclusion)

## Software Under Test (SUT)

Instrumented to control

**Thread A**

**Thread B**

**Thread C**

```
testfunc() {  
  JSContext *cx = JS_NewContext(r  
  if (cx) {  
    JS_BeginRequest(cx);  
    JS_DestroyContext(cx);  
  }  
}
```

Send event  
and block

Unblock thread

## Test in Concurrit DSL

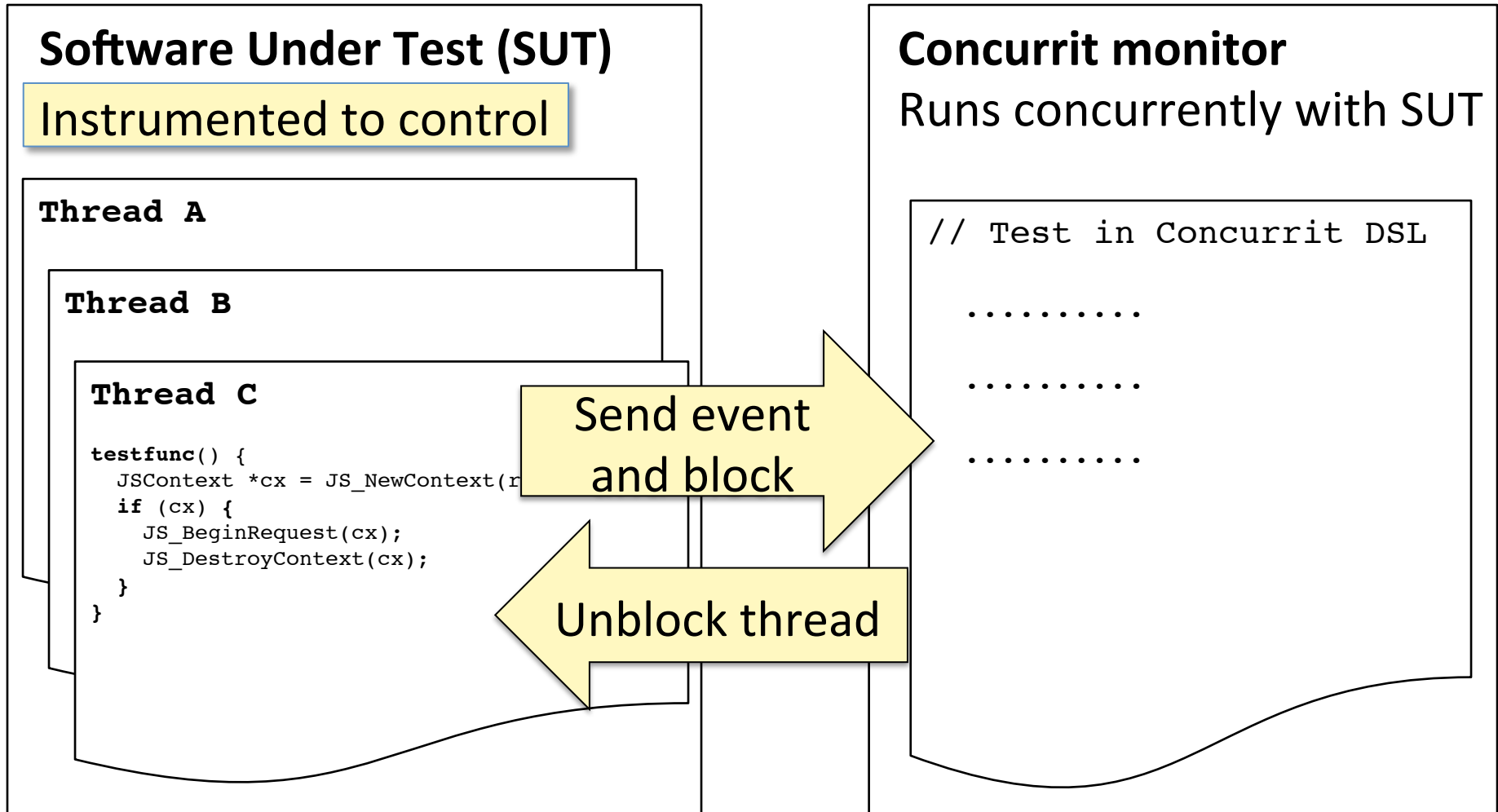
Runs concurrently with SUT

.....  
.....  
.....  
.....  
.....  
.....  
.....

**Kinds of events:** Memory read/write, function enter/return, function call, end of thread, at particular source line, user-defined

# Unit-testing programs with Concurrit

(What about integration tests?: Wait for conclusion)



**Kinds of events:** Memory read/write, function enter/return, function call, end of thread, at particular source line, user-defined

# Outline

- Bug report for Mozilla SpiderMonkey
- Write tests in Concurrit DSL to generate buggy schedule

## Simple schedules:

- Few schedules **BUT** not manifesting bug

### – All schedules:

- Manifests bug **BUT** too many schedules

### – Target buggy schedule in bug report

- Few schedules **AND** manifests bug



# Possible buggy schedule from bug report

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment 5](#) [[reply](#)] [[-](#)] [[reply](#)] [[-](#)]

At least one problem that I can see from the code is that `js_GC` does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
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outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls `js_DestroyContext` and thread C calls `js_NewContext`.

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch `rt->state` and eventually calls `js_GC`. The latter skips the above check and tries to to take the GC lock.

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At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when `rt->state` is `DOWN`.

Now the thread C enters the picture. It discovers under the GC lock in `js_NewContext` that the newly allocated context is the first one. Since `rt->state` is `DOWN`, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL  
  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
  
3:   WITH T IN [TA, TB, TC]  
  
4:   RUN T UNTIL COMPLETES  
}
```

# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL
```

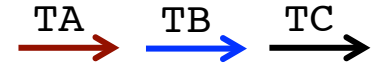
```
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()
```

```
2: LOOP UNTIL TA, TB, TC COMPLETE {
```

```
3:   WITH T IN [TA, TB, TC]
```

```
4:   RUN T UNTIL COMPLETES  
}
```

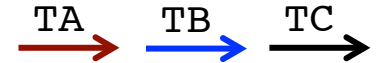
Wait until 3 distinct threads  
sending events



# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
3:   WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL COMPLETES  
}
```

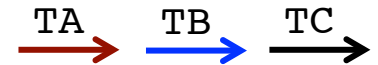
Loop until all 3 threads complete



# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
3:   WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL COMPLETES  
}
```

Pick one of the threads



○ Backtrack/choice point

# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
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3:   WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL COMPLETES  
}
```

Run selected thread  
until it completes

TA → TB → TC →

○ Backtrack/choice point

Thread  
completes

TA

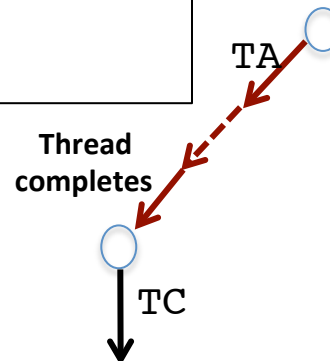
# First test: Run each thread sequentially until completion (No interleaving)

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// Test in Concurrit DSL  
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3:   WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL COMPLETES  
}
```

Pick one of the threads

TA → TB → TC →

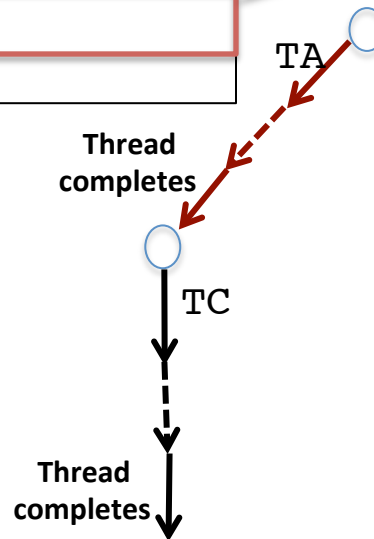
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# First test: Run each thread sequentially until completion (No interleaving)

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1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
  
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3:   WITH T IN [TA, TB, TC]  
  
4:   RUN T UNTIL COMPLETES  
  
}
```

Run selected thread until it completes





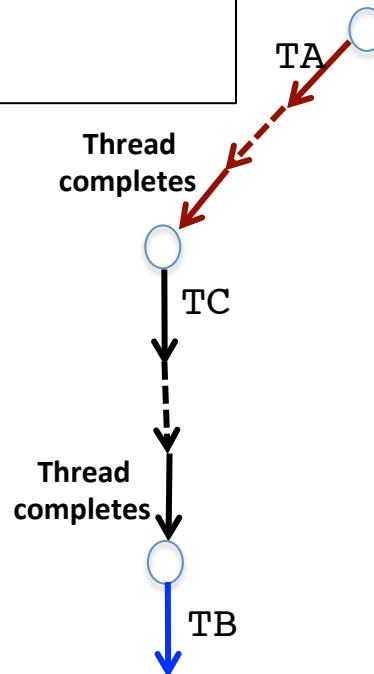
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4:   RUN T UNTIL COMPLETES  
}
```

Pick one of the threads

TA → TB → TC →

○ Backtrack/choice point



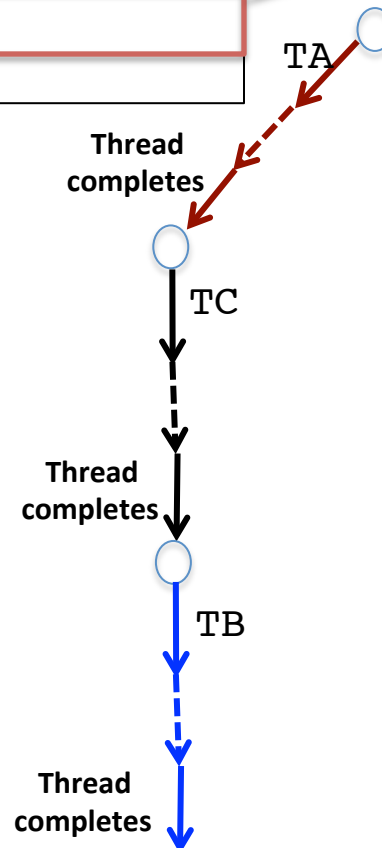
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}
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Run selected thread until it completes

TA → TB → TC →

○ Backtrack/choice point



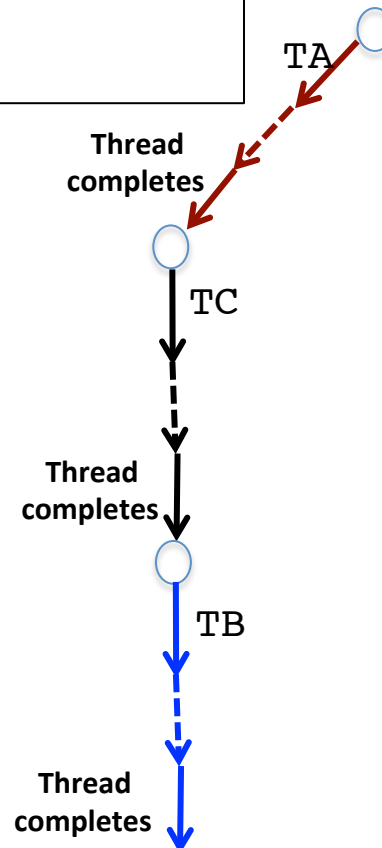
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```
// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
3:   BACKTRACK HERE WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL COMPLETES  
}
```

Pick a different thread  
when backtracked

TA → TB → TC →

○ Backtrack/choice point



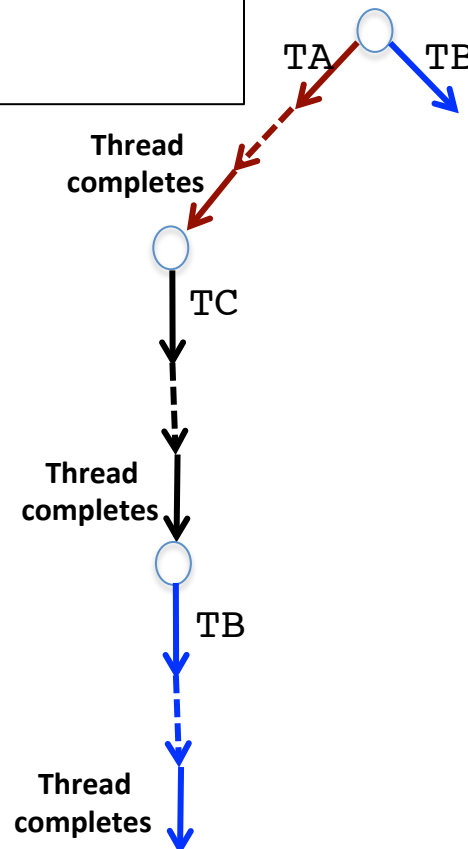
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}
```

Pick a different thread  
when backtracked

TA → TB → TC →

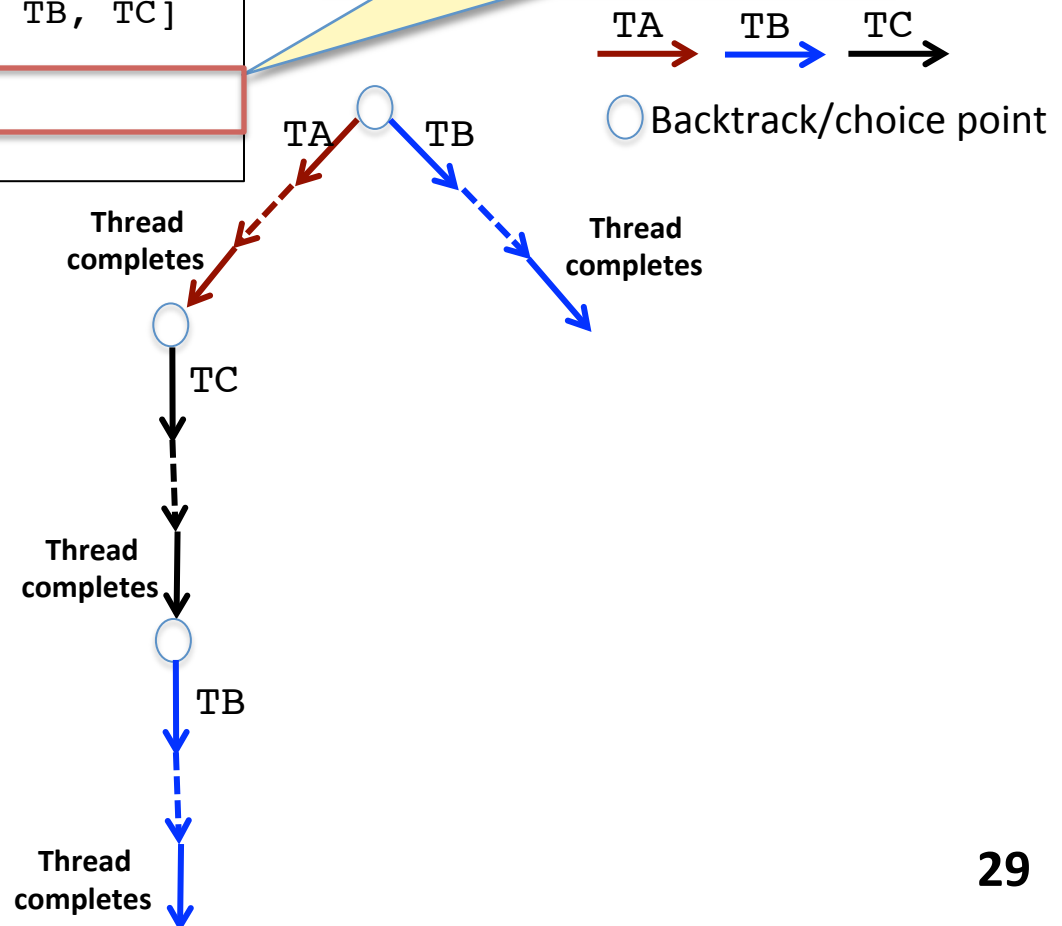
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}
```

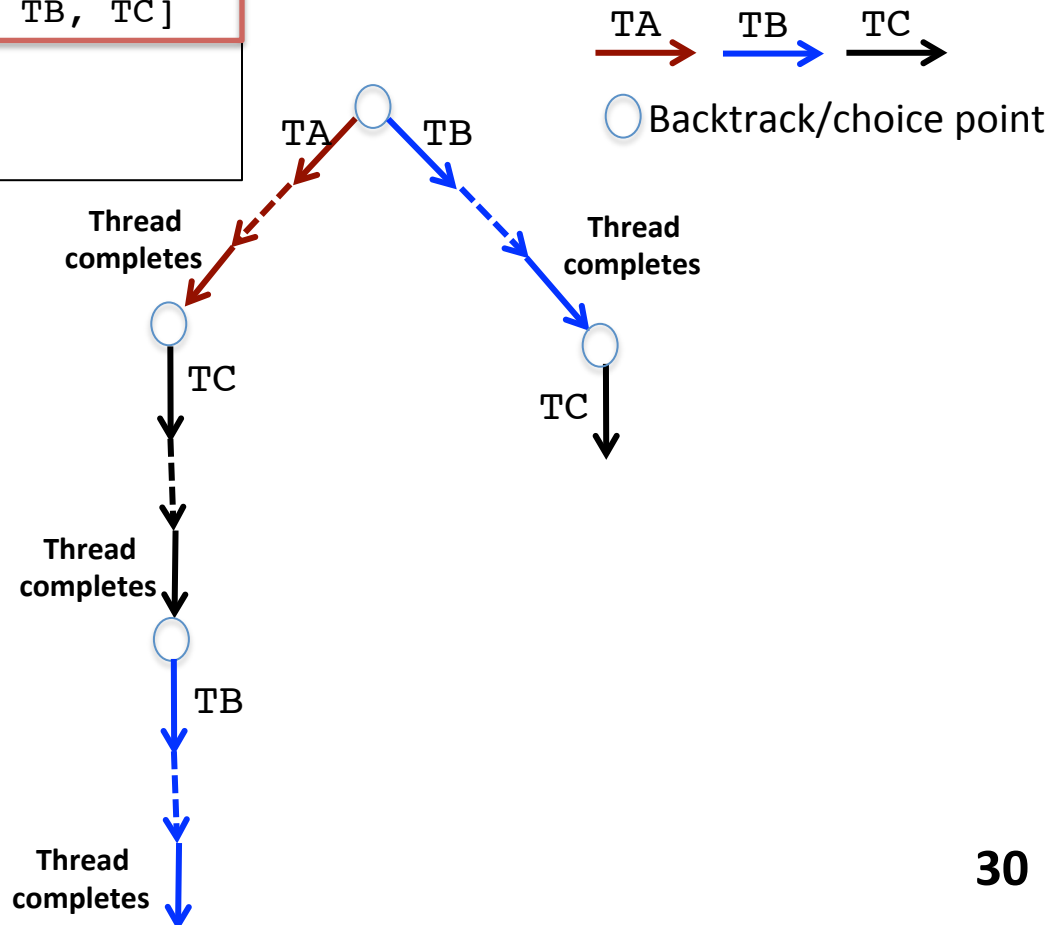
Run selected thread until it completes



# First test: Run each thread sequentially until completion (No interleaving)

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// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
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4:   RUN T UNTIL COMPLETES  
}
```

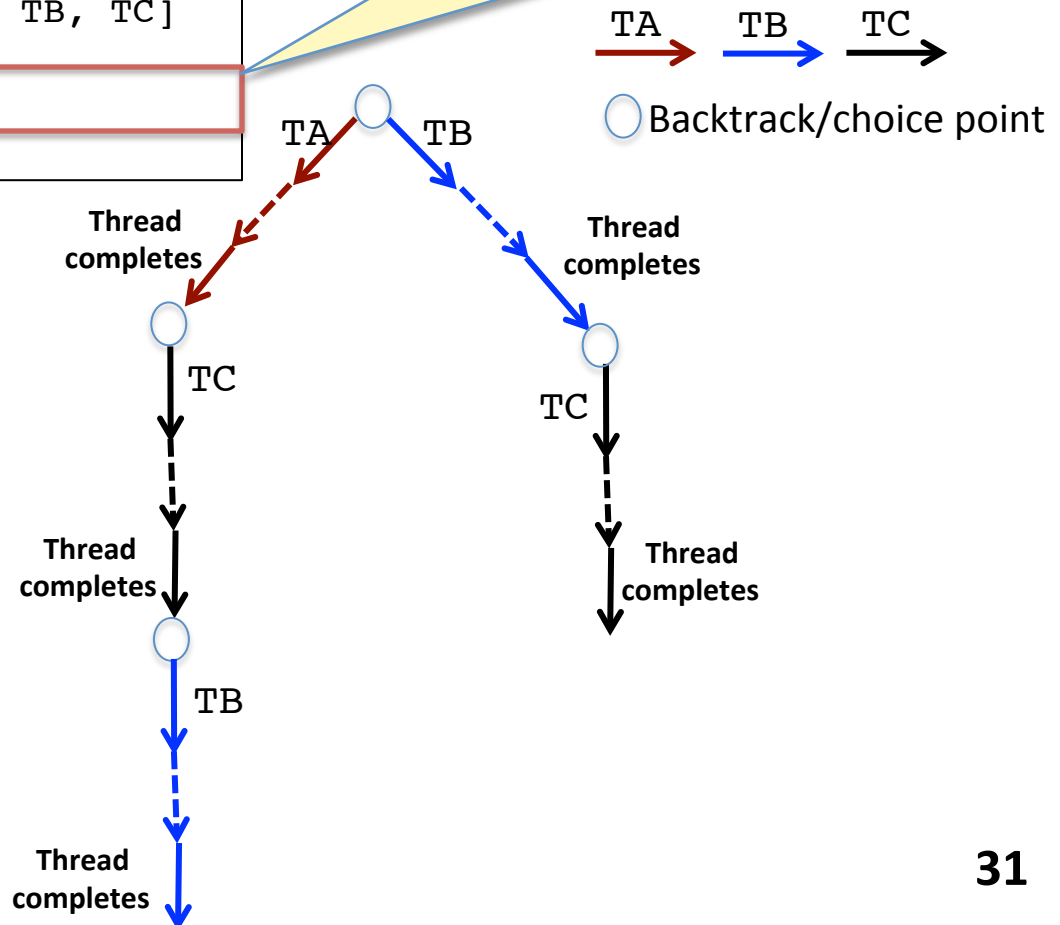
Pick a different thread  
when backtracked



# First test: Run each thread sequentially until completion (No interleaving)

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// Test in Concurrit DSL  
  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
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```

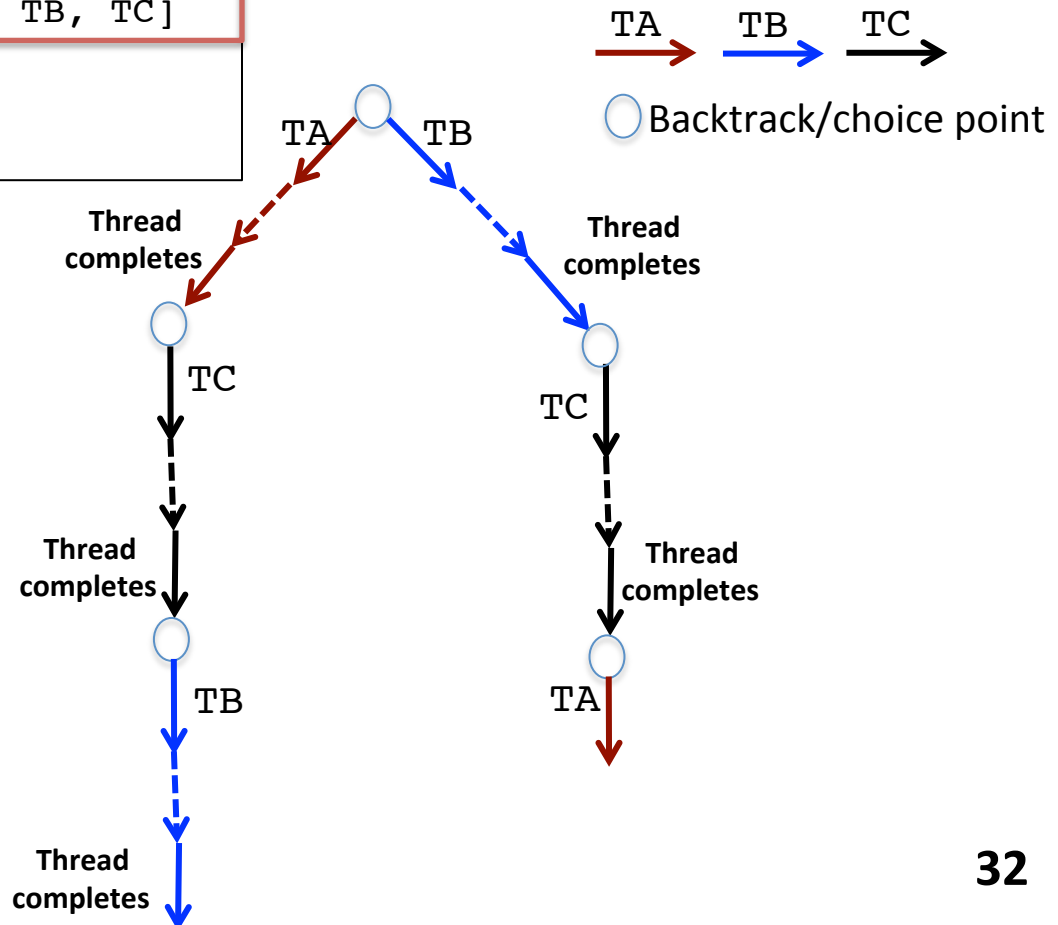
Run selected thread until it completes



# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
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}
```

Pick a different thread  
when backtracked

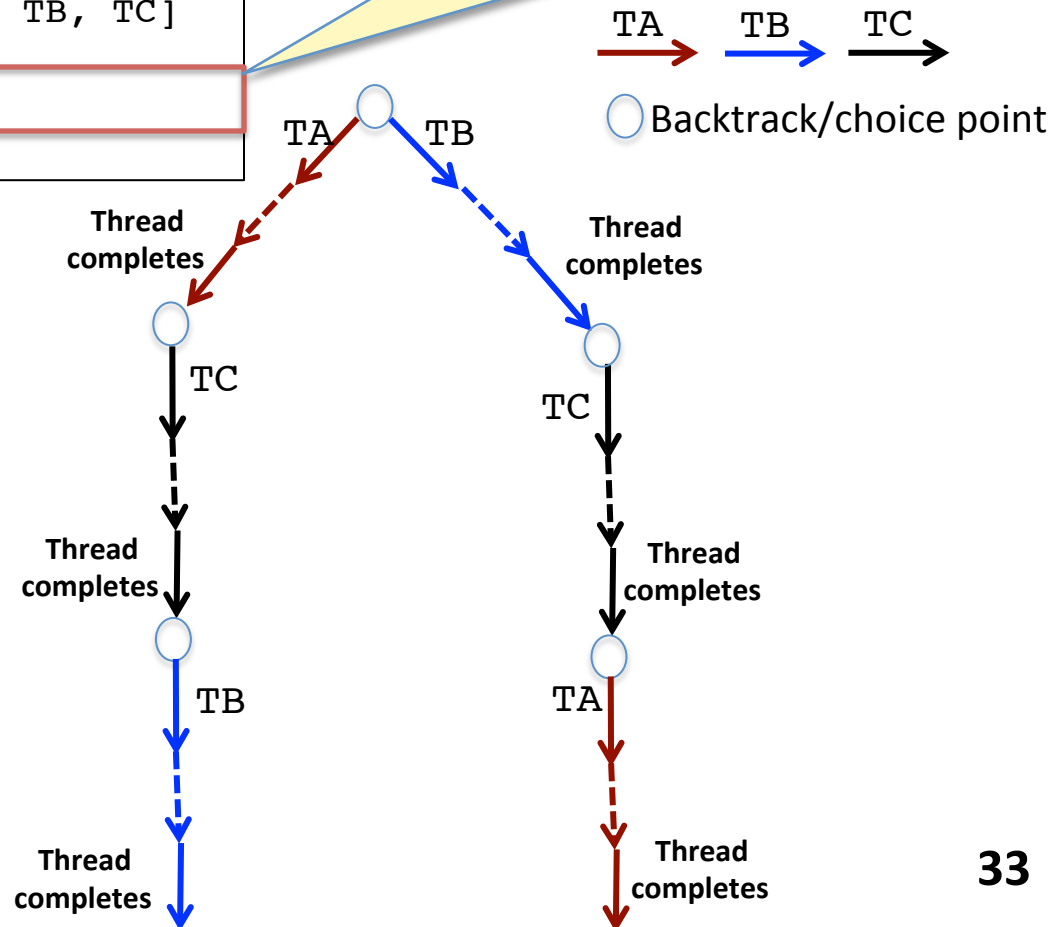




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2: LOOP UNTIL TA, TB, TC COMPLETE {  
3:   BACKTRACK HERE WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL COMPLETES  
}
```

Run selected thread until it completes



**First test: Run each thread sequentially until completion  
(No interleaving)**

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS( )

2: LOOP UNTIL TA, TB, TC COMPLETE {

3:     BACKTRACK HERE WITH T IN [TA, TB, TC]

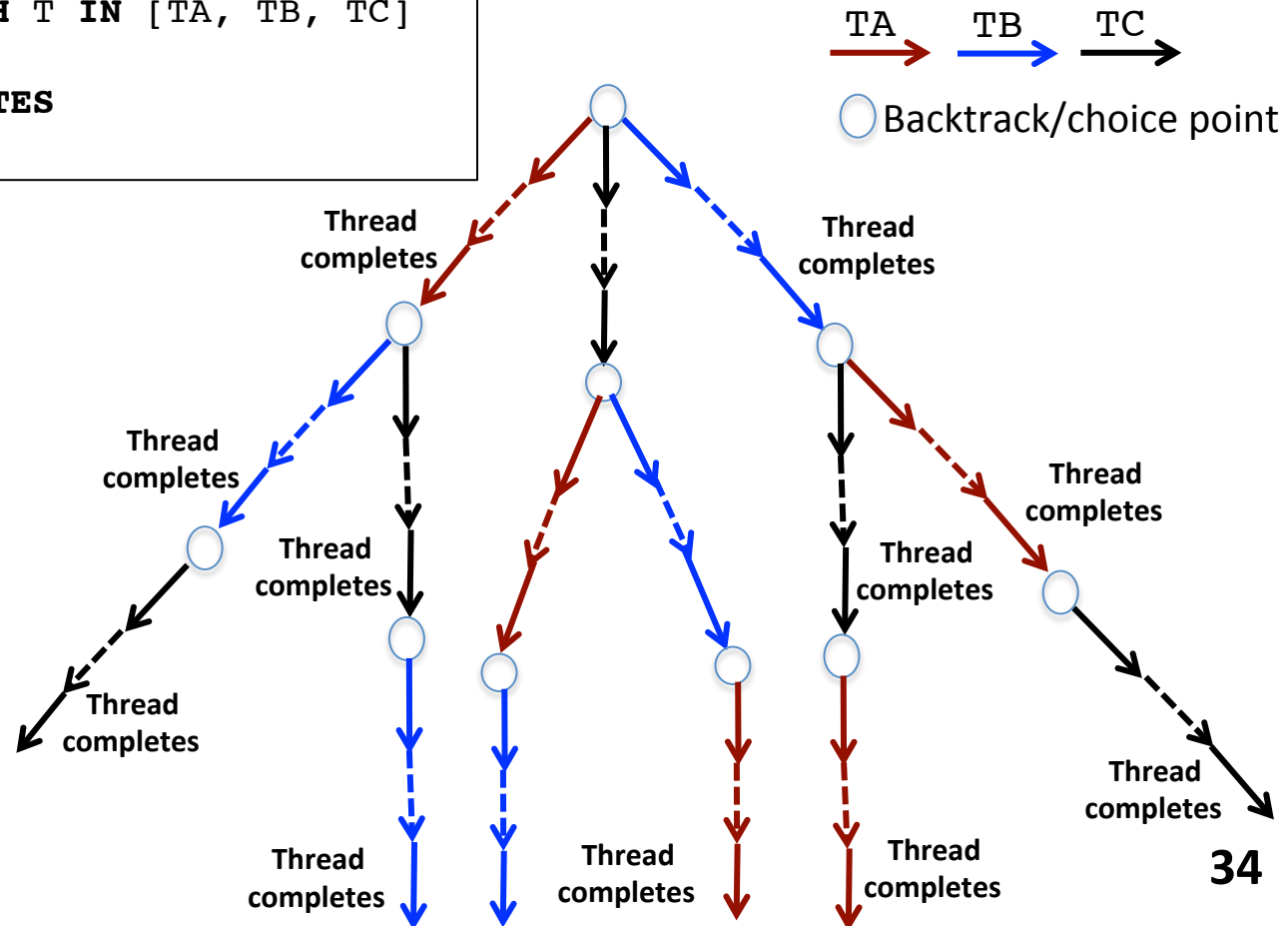
4:     RUN T UNTIL COMPLETES

}
```

## Result:

## 6 schedules

## No assertion failure!



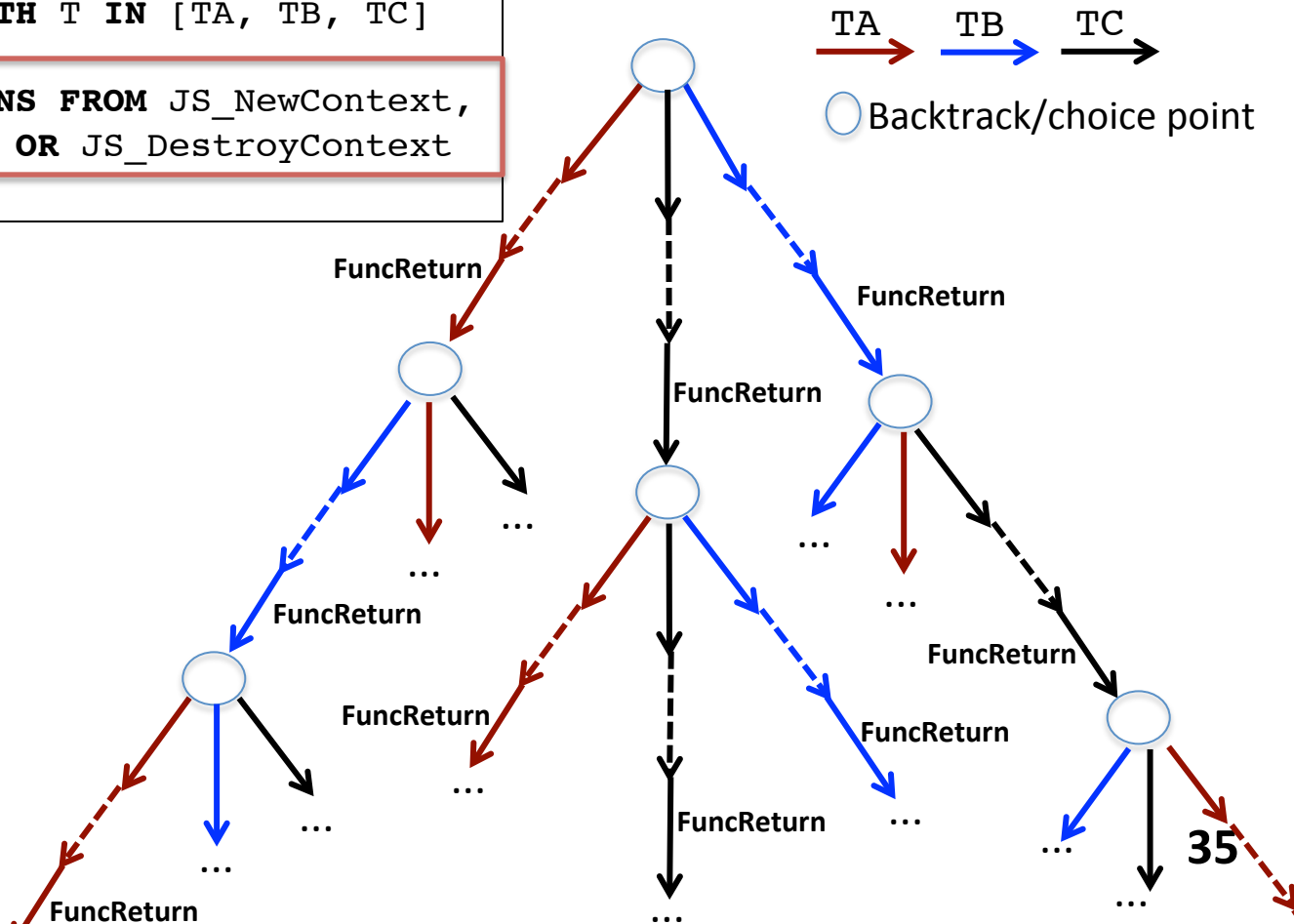
# Second test: Run each thread sequentially until it returns from function

```
// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
3:   BACKTRACK HERE WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL RETURNS FROM JS_NewContext,  
   JS_BeginRequest, OR JS_DestroyContext  
}
```

**Result:**

< 50 schedules

No assertion failure!



# Outline

- Bug report for Mozilla SpiderMonkey
- Write tests in Concurrit DSL to generate buggy schedule
  - **Simple schedules**
    - Few schedules **BUT** not manifesting bug
  - ➔ **All schedules**
    - Manifests bug **BUT** too many schedules
  - **Target buggy schedule in bug report**
    - Few schedules **AND** manifests bug

# First test: Run each thread sequentially until completion (No interleaving)

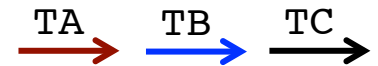
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4:     RUN T UNTIL COMPLETES  
}
```

# Generate all thread schedules

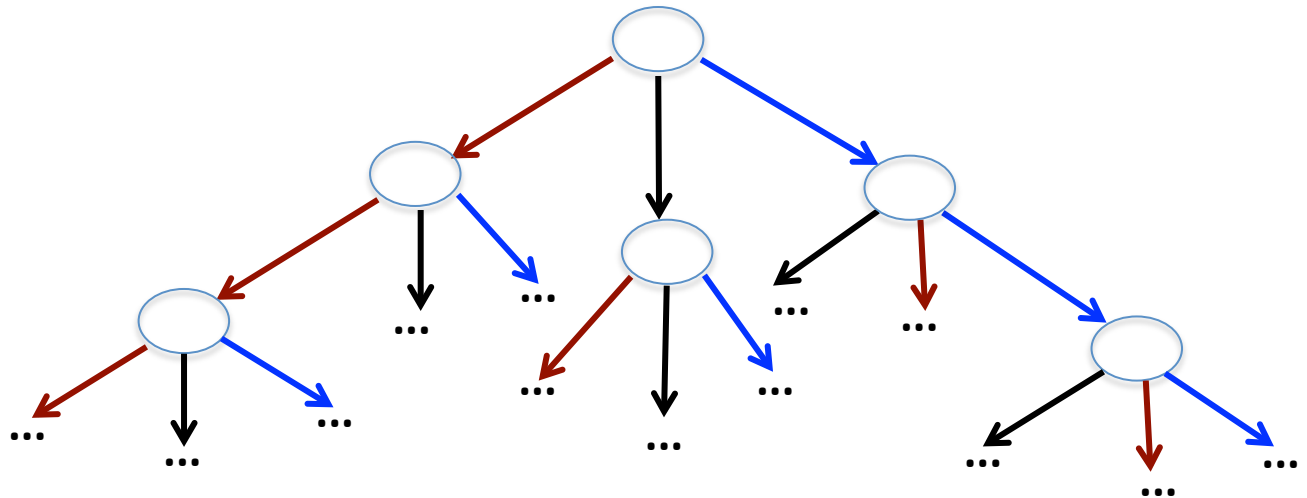
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// Test in Concurrit DSL  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
3:   BACKTRACK HERE WITH T IN [TA, TB, TC]  
4:   RUN T UNTIL NEXT EVENT  
}
```

## Result:

> 100,000 schedules  
Assertion failure  
after a night!



○ Backtrack/choice point



# What is different from (traditional) model checking?



## 1. Cannot control/instrument everything!

- Must tolerate uncontrolled non-determinism
- Backtrack-and-replay-prefix may fail

## 2. Localize the search

- To particular functions, operations, states, ...

**BUT:** Can express traditional model checking algorithms

- If every operation can be controlled
- Feasible for small programs, data structures, ...

# Outline

- Bug report for Mozilla SpiderMonkey
  - Write tests in Concurrit DSL to generate buggy schedule
    - **Simple schedules**
      - Few schedules **BUT** not manifesting bug
    - **All schedules**
      - Manifests bug **BUT** too many schedules
- ➡ **Target buggy schedule in bug report**
- Few schedules **AND** manifests bug



# Possible buggy schedule from bug report

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment 5](#) [[reply](#)] [[-](#)] [[reply](#)] [[-](#)]

At least one problem that I can see from the code is that `js_GC` does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls `js_DestroyContext` and thread C calls `js_NewContext`.

First thread A runs the last one so the latter skips the

```
static void * testfunc(void *ignore)
```

Threads A, B

```
JSContext *cx = JS_NewContext(rt, 0x1000);
if (cx) {
    JS_BeginRequest(cx);
    JS_DestroyContext(cx);
}

return NULL;
}
```

Thread C

At this stage the runs the GC and re DOWN.

m the runs

that ate is

Now the thread C enters the picture. It discovers under the GC lock in `js_NewContext` that the newly allocated context is the first one. Since `rt->state` is DOWN, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Generate all thread schedules

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

2: LOOP UNTIL TA, TB, TC COMPLETE {

3:     BACKTRACK HERE WITH T IN [TA, TB, TC]

4:     RUN T UNTIL NEXT EVENT

}
```

# Exploiting programmer's insights about bug

```
// Test in Concurr
```

```
1: TC = WAIT_FOR_T
```

```
2: TA = WAIT_FOR_D
```

```
3: TB = WAIT_FOR_D
```

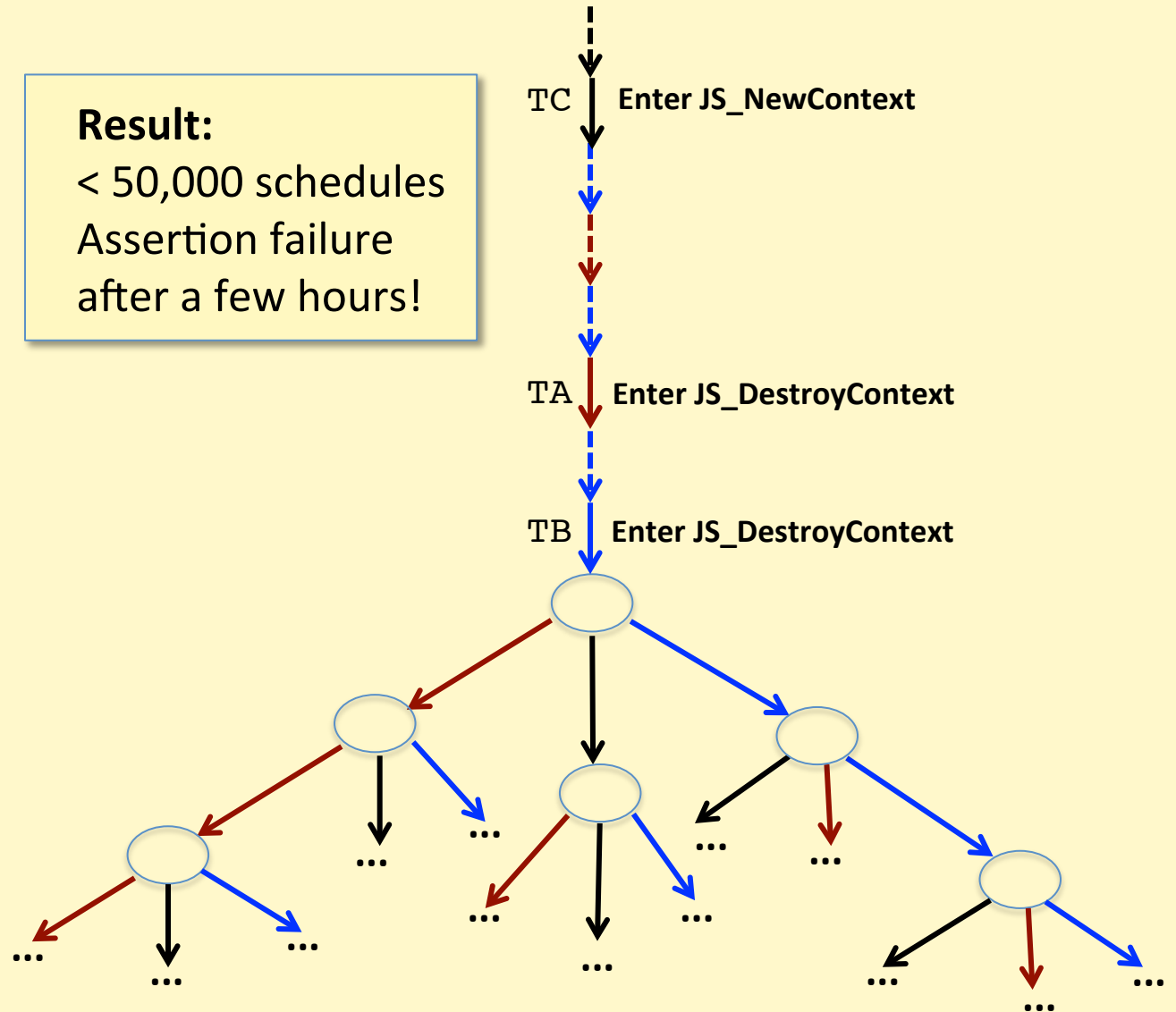
```
4: LOOP UNTIL TA,
```

```
5:   BACKTRACK HE
```

```
6:   RUN T UNTIL  
}
```

## Result:

< 50,000 schedules  
Assertion failure  
after a few hours!



# What is different from (traditional) model checking?

## 1. Cannot control/instrument everything!

- Must tolerate uncontrolled non-determinism
- Backtrack-and-replay-prefix may fail

## 2. Localize the search

- To particular functions, operations, states, ...

**BUT:** Can express traditional model checking algorithms

- If every operation can be controlled
- Feasible for small programs, data structures, ...

# Possible buggy schedule from bug report

- Shared variables involved in the bug:
  - **rt->state, rt->gcLock, rt->gcThread**
- Reschedule threads when accessing them.

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls `js_DestroyContext` and thread C calls `js_NewContext`.

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch `rt->state` and eventually calls `js_GC`. The latter skips the above check and tries to to **take the GC lock**.

Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, **sets `rt->state` to LANDING**, runs `the-last-context-cleanup`, runs the GC and then sets `rt->state` to DOWN.

At this stage the thread A gets the GC lock, **setup itself as the thread** that runs the GC and releases the GC lock to proceed with the GC when **`rt->state` is DOWN**.

Now the thread C enters the picture. It discovers under the GC lock in `js_NewContext` that the newly allocated context is the first one. Since **`rt->state` is DOWN**, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Exploiting programmer's insights about bug

```
// Test in Concurrit DSL

1: TC = WAIT_FOR_THREAD(ENTERS JS_NewContext)

2: TA = WAIT_FOR_DISTINCT_THREAD(ENTERS JS_DestroyContext)

3: TB = WAIT_FOR_DISTINCT_THREAD(ENTERS JS_DestroyContext)

4: LOOP UNTIL TA, TB, TC COMPLETE {

5:     BACKTRACK HERE WITH T IN [TA, TB, TC]

6:     RUN T UNTIL NEXT EVENT

}
```

# Exploiting programmer's insights about bug

```
// Test in Co
```

```
1: TC = WAIT
```

```
2: TA = WAIT
```

```
3: TB = WAIT
```

```
4: LOOP UNTIL
```

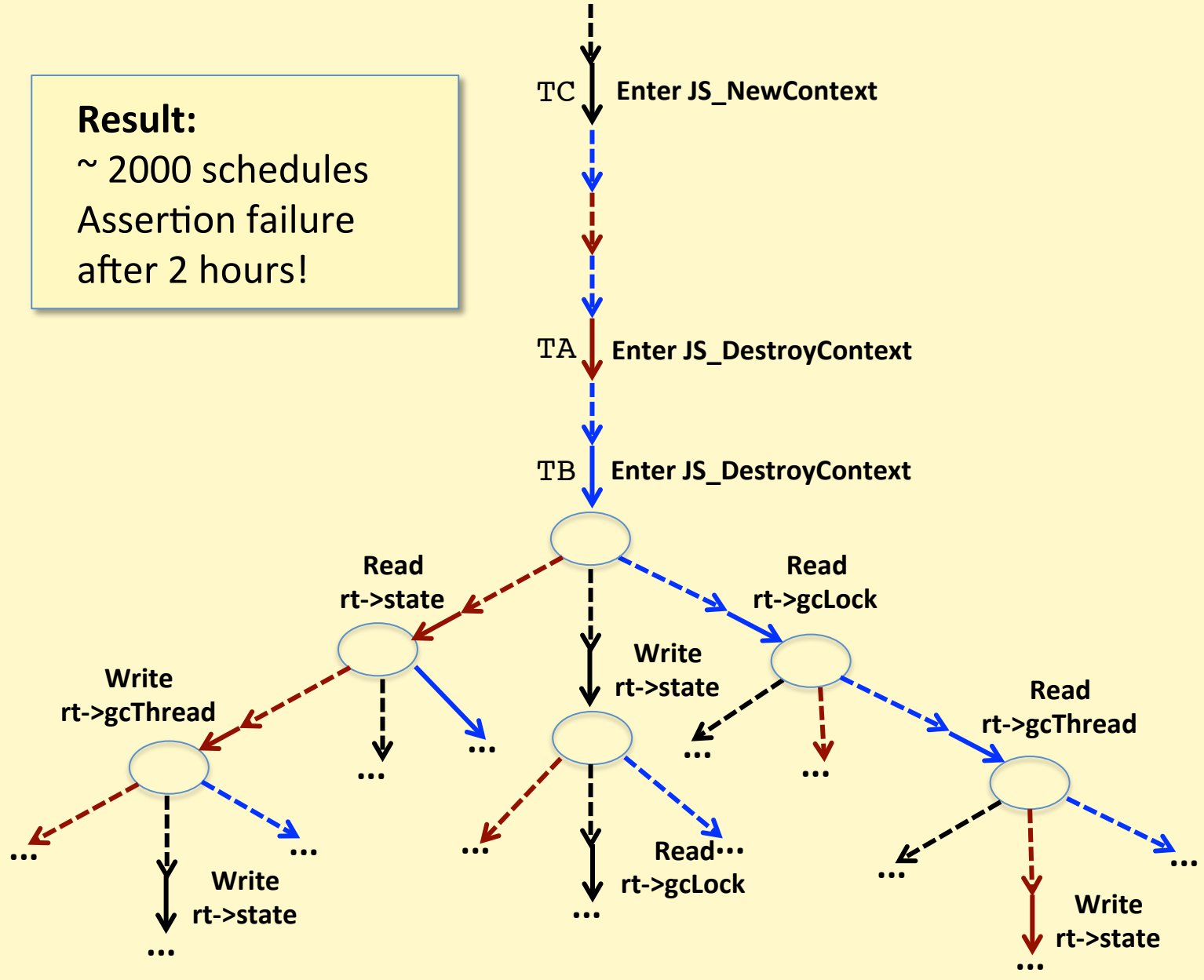
```
5: BACKTRA
```

```
6: RUN T U
```

```
}
```

**Result:**

~ 2000 schedules  
Assertion failure  
after 2 hours!



# Possible buggy schedule from bug report

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment 5](#) [[reply](#)] [[-](#)] [[reply](#)] [[-](#)]

At least one problem that I can see from the code is that `js_GC` does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

outside the GC lock. Now suppose there are calls `js_DestroyContext` and thread C calls

Setup

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch `rt->state` and eventually calls `js_GC`. The latter skips the above check and tries to take the GC lock.

Before this moment the thread B takes the runtime list, discovers that it is the last one, calls `the-last-context-cleanup`, runs the GC and

Fixed, known schedule  
for threads A and B

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when `rt->state` is DOWN.

Now the thread C enters the picture. It discovers that the GC lock is held by thread A. It calls `js_NewContext` that the newly allocated context has `rt->state` is DOWN, it releases the GC lock and proceeds with its initialization procedure. That procedure involves allocating atoms and it will happen when the thread A finishes its GC. According to the first stack trace from the [comment 4](#)

Unknown schedule  
for A and C



# Final test

```
// Test in Concurrit DSL
```

```
TC = WAIT_FOR_THREAD(  
    ENTERS JS_NewContext)
```

```
TA = WAIT_FOR_DISTINCT_THREAD(  
    ENTERS JS_DestroyContext)
```

```
TB = WAIT_FOR_DISTINCT_THREAD(  
    ENTERS JS_DestroyContext)
```

```
RUN TA UNTIL READS &rt->state IN js_GC
```

```
RUN TB UNTIL COMPLETES
```

```
RUN TA UNTIL WRITES &rt->gcThread IN js_GC
```

```
LOOP UNTIL TA, TC COMPLETE {
```

```
    BACKTRACK HERE WITH T IN [TA, TC]
```

```
    RUN T UNTIL READS OR WRITES MEMORY
```

```
}
```

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment](#)

At least one problem that I can see from the code is that js

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)  
    return;
```

outside the GC lock. Now  
calls js\_DestroyContext

Setup

First thread A removes its context from the runtime list. Th  
the last one so thread does not touch rt->state and eventual  
latter skips the above c

Before this moment the t  
runtime list, discovers  
the-last-context-cleanup

Fixed, known schedule  
for threads A and B

At this stage the thread A gets the GC lock, setup itself as  
runs the GC and releases the GC lock to proceed with the GC  
DOWN.

Now the thread C enters  
js\_NewContext that the n  
rt->state is DOWN, it re  
initialization procedure  
atoms and it will happen  
to the first stack trace from the [comment 4](#).

Unknown schedule  
for A and C

# Final test

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT [Comment 5](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

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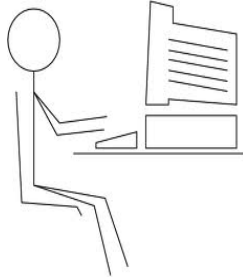
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Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, sets rt->state to LANDING, runs the-last-context-cleanup, runs the GC and then sets rt->state to DOWN.

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when rt->state is DOWN.

Now the thread C enters the picture. It discovers under the GC lock in js\_NewContext that the newly allocated context is the first one. Since rt->state is DOWN, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).



Software Under Test

.....  
.....

+

```
// Test in Concurrit DSL

TC = WAIT_FOR_THREAD(
    ENTERS JS_NewContext)

TA = WAIT_FOR_DISTINCT_THREAD(
    ENTERS JS_DestroyContext)

TB = WAIT_FOR_DISTINCT_THREAD(
    ENTERS JS_DestroyContext)

RUN TA UNTIL READS &rt->state IN js_GC

RUN TB UNTIL COMPLETES

RUN TA UNTIL WRITES &rt->gcThread IN js_GC

LOOP UNTIL TA, TC COMPLETE {

    BACKTRACK HERE WITH T IN [TA, TC]

    RUN T UNTIL READS OR WRITES MEMORY

}
```

Triggers assertion failure  
in < 30 thread schedules  
(Add to regression test suit)

# Implementation/Evaluation

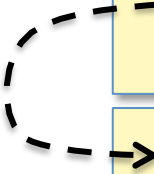
- **Implementation:** DSL embedded in C++
  - Prototype: <http://code.google.com/p/concurrit/>
- Wrote concise tests for (real/manually-inserted) bugs in well-known benchmarks
  - Reproducing bugs
    - using < 20 lines of DSL code, after < 30 schedules
  - **Inspect:** bbuf, bzip2, pbzip2, pfscan
  - **PARSEC:** dedup, streamcluster
  - **RADBench:** SpiderMonkey 1/2, Mozilla NSPR 1/2/3
    - **Ongoing:** Apache httpd, Chromium, Memcached
- Can write various model checking algorithms (next slide)

# Default search policies

```
EXPLORE_ALL_SCHEDULES(THREADS) {  
  LOOP UNTIL ALL THREADS COMPLETE {  
    BACKTRACK HERE WITH T IN THREADS  
    RUN T UNTIL NEXT EVENT  
  }  
}
```

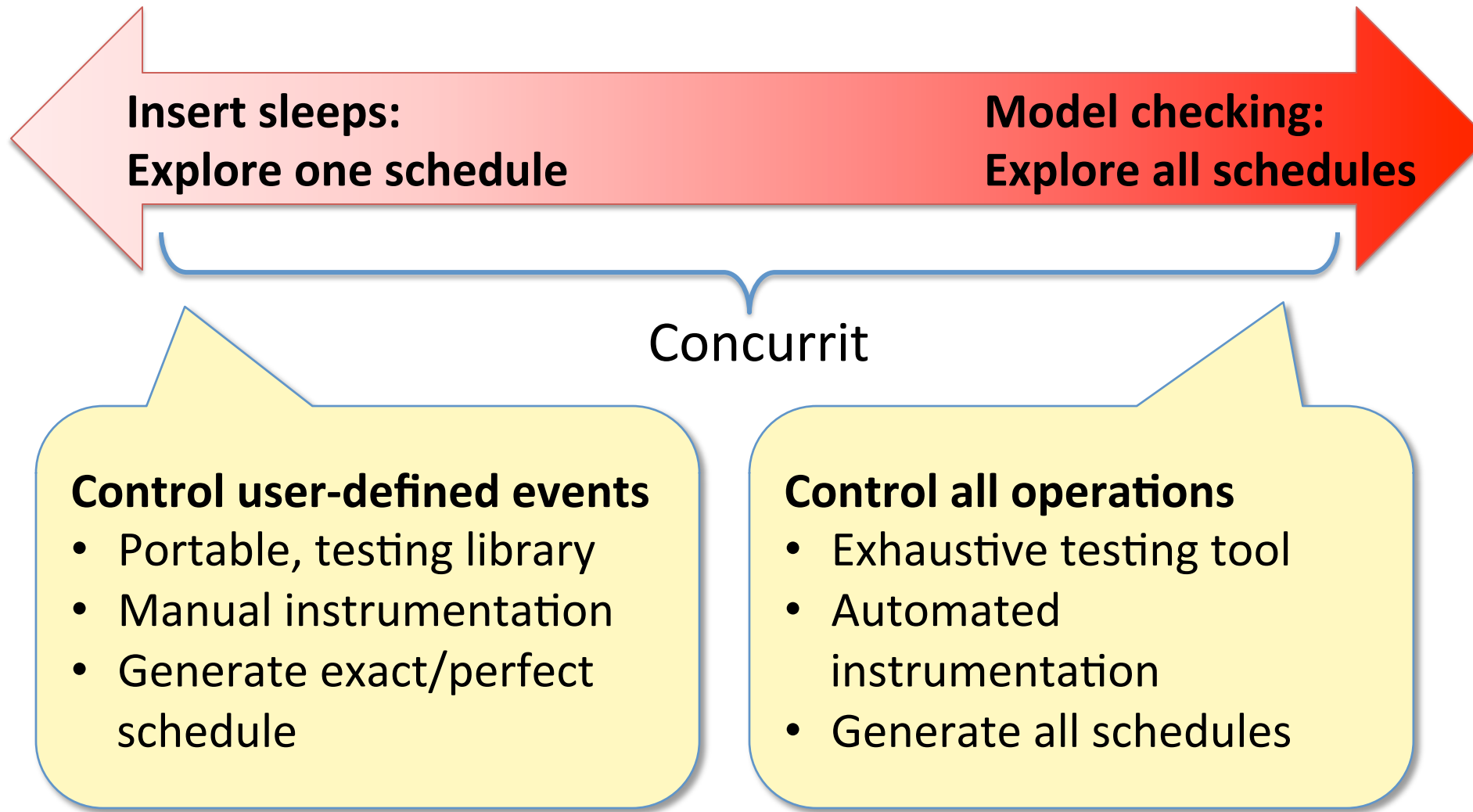
```
EXPLORE_TWO_CONTEXT_BOUNDED_SCHEDULES(THREADS) {  
  BACKTRACK HERE WITH T1 IN THREADS  
  BACKTRACK HERE LOOP NONDETERMINISTICALLY {  
    RUN T1 UNTIL NEXT EVENT  
  }  
  
  BACKTRACK HERE WITH T2 IN [THREADS EXCEPT T1]  
  BACKTRACK HERE LOOP NONDETERMINISTICALLY {  
    RUN T2 UNTIL NEXT EVENT  
  }  
}
```

```
-- EXPLORE_THREADS_UNTIL_COMPLETION(THREADS)  
}
```



```
EXPLORE_THREADS_UNTIL_COMPLETION(THREADS) {  
  LOOP UNTIL ALL THREADS COMPLETE {  
    BACKTRACK HERE WITH T IN THREADS  
    RUN T UNTIL COMPLETION  
  }  
}
```

# Positioning Concurrit: Usage scenarios



**Insert sleeps:**  
**Explore one schedule**

**Model checking:**  
**Explore all schedules**

Concurrit

## **Control user-defined events**

- Portable, testing library
- Manual instrumentation
- Generate exact/perfect schedule

## **Control all operations**

- Exhaustive testing tool
- Automated instrumentation
- Generate all schedules

# Unit-testing programs with Concurrit

## Software Under Test (SUT)

Instrumented to control

**Thread A**

**Thread B**

**Thread C**

```
testfunc() {  
  JSContext *cx = JS_NewContext(r  
  if (cx) {  
    JS_BeginRequest(cx);  
    JS_DestroyContext(cx);  
  }  
}
```

Send event  
and block

Unblock thread

## Test in Concurrit DSL

Runs concurrently with SUT

.....

.....

.....

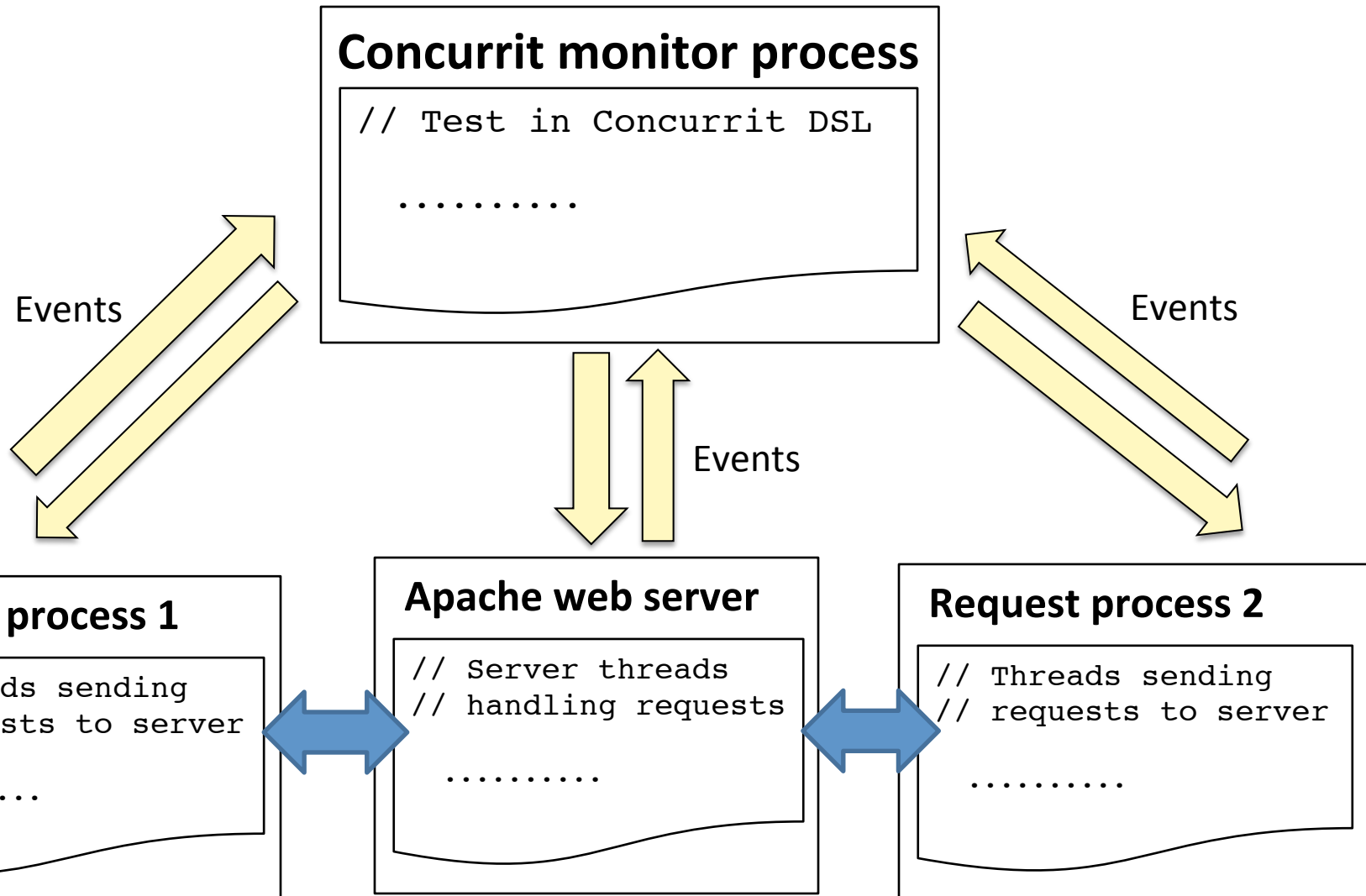
.....

.....

.....

# Ongoing work: Integration testing

## Controlling multi-process/distributed applications



# Approaches to controlling thread schedules

**Test run:** A set of executions of the test driver.

**Success:** At least one execution in the run hits the bug.

